

Compact Inverters

FRENIC-Mini Series





Compact



And















High Performance and Multipurpose

Fully Compatible with Existing Products

Easy Operation and Maintenance

New Compact Inverter

High Performance Compact Body. Get Our Most User-Friendly Inverter yet!



NEXT Generation! COMPACT INVERTER FRENIC

FUJI ELECTRIC INVERTERS

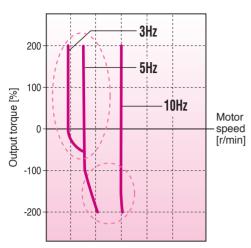
High Perfomance Compact Body. Welcome to the NEXT Generation of Compact Inverter

With its functionality, compact design, simple operation, and global compatibility, the new FRENIC-Mini elevates the performance of a wide range of devices and equipment--including conveyors, fans, pumps, centrifugal separators, and food processing machines--to give you the system integration, energy efficiency, reduced labor, and lower overall costs you're looking for.

Energy Efficient Network Capabilities Global Compatibility



High Performance and Multipurpose



Dynamic Torque Vector Control System

Fuji Electric original dynamic torque vector control system is known for its top-of-the line performance, delivering stabile torque output even at low speeds. This feature has a wide range of applications, including conveyors and high-inertia loads that demand high starting torque.

Slip Compensation shortens setting time

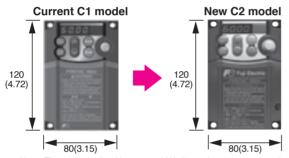
The slip compensation controller works with voltage tuning for even more accurate speed control at low velocity. This reduces speed control variability and stabilizing creep speed for more accurate stopping in conveyors and similar equipment.

Fastest CPU Processor in its Class

Advanced CPU processes data at twice the speed of our current model



Full Compatibility and User Friendly Design



Note: Three-phase 200V 0.1-0.75kW dimensions shown (mm(inch))

External dimensions	Interchangeable
Installed dimensions	Interchangeable
Number of terminals	Same for both main circuit and controllers
Terminal position	Compatible terminal wire length
Function codes	Compatible function codes
RS-485 communication	Shared communications protocol



Easy Operation and Maintenance

Usability

Delivers all the usability of the C1. Provides volume of frequency and the same ease of operation as the current model.

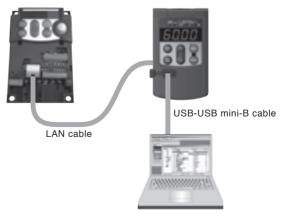


Improve Maintainability

Function	Description
Mock malfunction	Select a function to set off a mock alarm
Number of startups	Count the total number of ON/OFF run cycles
Cumulative motor running time	Monitor motor run time
Total power	Set to measure total power consumption
Trip history	Saves and displays information on up to four past trips

USB Keypad

Optional USB keypad available. Enhanced PC loader software (FRENIC Loader) connectivity.



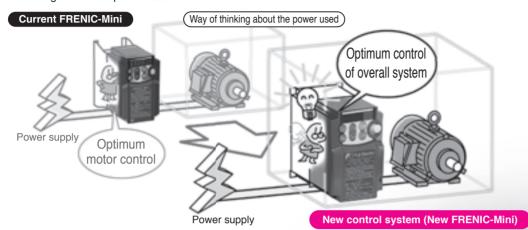
· FRENIC Loader available as a free download



Energy Optimization

Optimum Energy Control

Motor tuning minimizes power loss



PID Control Function

Permits motor operation while controlling temperature, pressure, and flow rate without the use of a temperature controller or other external device

Cooling Fan ON/OFF Control Function

The cooling fan can be switched off when the fan or pump is not running to reduce both noise and energy consumption

Synchronous Motor Control

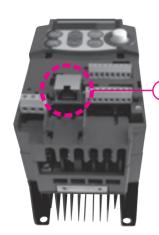
Use of sensorless synchronous motor control together with the motor can reduce energy consumption



Network Capabilities

RS-485 Communications Port as Standard

Communications can be controlled through the standard RS-485 communications port using the Modbus-RTU or Fuji Electric inverter protocol



RS-485 Communication Port



Other Features

Functions for User Applications

V/F (non-linear 3 step) Two motor parameter sets Brake signal (brake release signal) Rotational direction control (prevent forward/reverse movement)

Global Standard

EC Directives (CE making)



UL standard (cUL certification)



Variation

Nominal Applied	Three-phase	Three-phase	Single-phase	Single-phase
Motor (kW)[HP]	200V series	400V series	200V series	100V series
Standard specifications				
Without EMC filter type				
0.1 [1/8]	FRN0001C2S-2		FRN0001C2S-7□	FRN0001C2S-6U
0.2 [1/4]	FRN0002C2S-2□		FRN0002C2S-7□	FRN0002C2S-6U
0.4 [1/2]	FRN0004C2S-2□	FRN0002C2S-4□	FRN0004C2S-7□	FRN0003C2S-6U
0.75 [1]	FRN0006C2S-2□	FRN0004C2S-4□	FRN0006C2S-7□	FRN0005C2S-6U
1.5 [2]	FRN0010C2S-2□	FRN0005C2S-4□	FRN0010C2S-7□	
2.2 [3]	FRN0012C2S-2□	FRN0007C2S-4□	FRN0012C2S-7□	
3.7 [5]	FRN0020C2S-2□	FRN0011C2S-4□		
5.5 [7.5]	FRN0025C2S-2□	FRN0013C2S-4□		
7.5 [10]	FRN0033C2S-2□	FRN0018C2S-4□		
11 [15]	FRN0047C2S-2□	FRN0024C2S-4□		
15 [20]	FRN0060C2S-2□	FRN0030C2S-4□		
Destination	A(Asia), U(USA)	A(Asia), C(China), E	E(Europe), U(USA)	U(USA)
Semi-standard specifica	tions			
	1110113			
EMC filter built-in type				
0.1 [1/8]			FRN0001C2E-7E	
0.2 [1/4]			FRN0002C2E-7E	
0.4 [1/2]		FRN0002C2E-4E	FRN0004C2E-7E	
0.75 [1]		FRN0004C2E-4E	FRN0006C2E-7E	
1.5 [2]		FRN0005C2E-4E	FRN0010C2E-7E	
2.2 [3]		FRN0007C2E-4E	FRN0012C2E-7E	
3.7 [5]		FRN0011C2E-4E		
5.5 [7.5]		FRN0013C2E-4E		
7.5 [10]		FRN0018C2E-4E		
11 [15]		FRN0024C2E-4E		
15 [20]		FRN0030C2E-4E		
Destination		E(Eur	ope)	

How To Read Model Number FRN 0010 C 2 S - 4 A

			 1	010			T /	1		
Code	Series Name					_	ТΤ	ı	Code	Destination/Manual
FRN	FRENIC series								Α	Asia/English
									С	China/Chinese
	cable Current Rating								Е	Europe/English
This value	shows an amperage rating								U	USA/English
	0001~0060									
									Code	Input Power Source
Code	Application Range								2	Three-phase 200V
С	Compact								4	Three-phase 400V
	I	1							6	Single-phase 100V
Code	Developed Inverter Series								7	Single-phase 200V
2	2-series									
		-								
Code	Enclosure									
S	Standard (IP20) (UL Open Type)									
F	EMC filter built-in type									



The contents of this catalog are provided to help you select the product model that is best for you. Before actual use, be sure to read the User's Manual thoroughly to assure correct operation.

Standard Model

Specifications

■Three-phase 200V series

	Item						S	pecification	ıs					
Inpu	ut power source		Three-phas	se 200V										
Тур	е		FRN C2S-2A, FRN C2S-2U											
(FR	N C2S-	·2△, △=A, U)												
			0001	0002	0004	0006	0010	0012	0020	0025	0033	0047	0060	
Nor	Nominal applied motor[kW](\triangle =A)		0.1	0.2	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	
Nor	ninal applied mo	1/8	1/4	1/2	1	2	3	5	7.5	10	15	20		
	Rated capacity	0.30	0.57	1.3	2.0	3.5	4.5	7.2	9.5	12	17	22		
sbu	Rated voltage[V]	Three-phas	se 200 to 240	V (With AVR)								
ratir	Rated current[/	A](*1)	0.8(0.7)	1.5(1.4)	3.5(2.5)	5.5(4.2)	9.2(7.0)	12.0(10.0)	19.1(16.5)	25.0(23.5)	33.0(31.0)	47.0(44.0)	60.0(57.0)	
Output ratings	Overload capa	bility									of rated current for 1min or of rated current for 0.5s			
	Rated frequenc	cy[Hz]	50, 60Hz											
	Phases, Voltag	e, Frequency	Three-phas	Three-phase, 200 to 240V, 50/60Hz										
Input ratings	Voltage/Freque	ncy variations	Voltage: +1	Voltage: +10 to -15% (Voltage unbalance : 2% or less), Frequency: +5 to -5%										
t rat	Rated current[A]	(with DCR)	0.57	0.93	1.6	3.0	5.7	8.3	14.0	21.1	28.8	42.2	57.6	
ndul		(without DCR)	1.1	1.8	3.1	5.3	9.5	13.2	22.2	31.5	42.7	60.7	80.0	
	Required power sup	pply capacity[kVA]	0.2	0.3	0.6	1.1	2.0	2.9	4.9	7.4	10	15	20	
ا ور	Torque[%]		150		100		50	30		20				
Braking	DC injection br	aking	Starting fre	equency: 0.0	to 60.0Hz, Br	aking time: 0	.0 to 30.0s E	Braking level:	0 to 100%					
В	Braking transis	tor	_		Built-in									
App	licable safety st	andards	UL508C, E	N 61800-5-1	:2007									
Enc	losure (IEC 605	29)	IP20 (IEC	60529:1989)	/ UL open typ	pe (UL50)								
Coc	ooling method		Natural cod	oling			Fan coolin	g						
Wei	ght / Mass[kg(lb	s)]	0.6(1.3)	0.6(1.3)	0.7(1.5)	0.8(1.8)	1.7(3.7)	1.7(3.7)	2.5(5.5)	3.1(6.8)	3.1(6.8)	4.5(9.8)	4.5(9.8)	

^{*1} The load shall be reduced so that the continuous operating current is the rated current in parenthesis or less if the carrier frequency is set to 3kHz or above or ambient temperature exceeds 40°C (104°F).

Three-phase 400V series

	Item					:	Specifications					
Inpu	ıt power source		Three-phase 400V									
Тур	е		FRNC2S-4A, FRNC2S-4C									
(FRI	N □□□□ C2S-4△	, △=A, C, E, U)	FRNC2S-4E, FRNC2S-4U									
			0002	0004	0005	0007	0011	0013	0018	0024	0030	
Nor	ninal applied mot	tor[kW]	0.4	0.75	1.5	2.2	3.7(△=A, C)	5.5	7.5	11	15	
(△:	=A, C, E)						4.0(△=E)					
Non	ninal applied mot	or[HP](△=U)	1/2	1	2	3	5	7.5	10	15	20	
	Rated capacity	kVA]	1.3	2.3	3.2	4.8	8.0	9.9	13	18	22	
sbu	Rated voltage[\	/]	Three-phase	380 to 480V (Wi	th AVR)							
ratir	Rated current[A](*1)		1.8(1.5)	3.1(2.5)	4.3(3.7)	6.3(5.5)	10.5(9.0)	13.0	18.0	24.0	30.0	
Output ratings	Overload capab	oility		150% of rated current for 1min 150% of rated current for 1min or 200% of rated current for 0.5s (If the rated current is in parenthesis) 150% of rated current for 0.5s								
	Rated frequenc	y[Hz]	50, 60Hz	i0, 60Hz								
	Phases, Voltage	e, Frequency	Three-phase,	Three-phase, 380 to 480V, 50/60Hz								
Input ratings	Voltage/Frequer	ncy variations	Voltage: +10 t	to -15% (Voltage	unbalance : 2%	6 or less), Frequ	ency: +5 to -5%	1				
t rat	Rated current[A]	(with DCR)	0.85	1.6	3.0	4.4	7.3	10.6	14.4	21.1	28.8	
lnpu		(without DCR)	1.7	3.1	5.9	8.2	13.0	17.3	23.2	33.0	43.8	
	Required power sup	ply capacity[kVA]	0.6	1.1	2.0	2.9	4.9	7.4	10	15	20	
g	Torque[%]		100		50	30		20				
Braking	DC injection bra	aking	Starting freque	ency: 0.0 to 60.0	OHz, Braking tim	ne: 0.0 to 30.0s	Braking level: 0	to 100%				
ď	Braking transist	or	Built-in									
App	licable safety sta	ındards	UL508C, EN 61800-5-1:2007									
Enc	losure (IEC 6052	29)	IP20 (IEC 60529:1989) / UL open type (UL50)									
Coc	oling method		Natural coolin	Natural cooling Fan cooling								
Wei	ght / Mass[kg(lbs	s)]	1.2(2.6)	1.3(2.9)	1.7(3.7)	1.7(3.7)	2.5(5.5)	3.1(6.8)	3.1(6.8)	4.5(9.8)	4.5(9.8)	

^{*1} The load shall be reduced so that the continuous operating current is the rated current in parenthesis or less if the carrier frequency is set to 3kHz or above or ambient temperature exceeds 40°C (104°F).

Specifications

Single-phase 200V/100V series

	Item						Specifi	cations					
Inpi	ut power source	Single-phas	e 200V					Single-phas	e 100V				
Тур	е		FRN C2S-7A, FRN C2S-7C					FRN C2S-6U					
(FRI	N □□□□ C2S-□△, △ =A,	C, E, U)	FRNC2S-7E, FRNC2S-7U										
			0001	0002	0004	0006	0010	0012	0001	0002	0003	0005	
Nor	ninal applied motor[kW]	0.1	0.2	0.4	0.75	1.5	2.2	0.1	0.2	0.4	0.75	
(△:	=A, C, E)												
Nor	ninal applied motor[HP]	1/8	1/4	1/2	1	2	3	1/8	1/4	1/2	1		
	Rated capacity[kVA]	0.30	0.57	1.3	2.0	3.5	4.5	0.26	0.53	0.95	1.6		
sbu	Rated voltage[V]		Three-phase	200 to 240V	(With AVR)								
ratir	Rated current[A](*1)		0.8(0.7)	1.5(1.4)	3.5(2.5)	5.5(4.2)	9.2(7.0)	12.0(10.0)	0.7	1.4	2.5	4.2	
Output ratings	Overload capability			0% of rated current for 1 min 0% of rated current for 1 min or 200% of rated current for 0.5s (If the rated current is in parenthesis)						ed current for ated current f			
	Rated frequency[Hz]		50, 60Hz	50, 60Hz									
	Phases, Voltage, Free	quency	Single-phase	Single-phase, 200 to 240V, 50/60Hz Single-phase 100 to 120V, 50/60Hz									
Input ratings	Voltage/Frequency va	riations	Voltage: +10	Voltage: +10 to -10%, Frequency: +5 to -5%									
t rat	Rated current[A] (with D	CR)	1.1	2.0	3.5	6.4	11.6	17.5	2.2	3.8	6.4	12.0	
ndu	(withou	ıt DCR)	1.8	3.3	5.4	9.7	16.4	24.0	3.6	5.9	9.5	16.0	
	Required power supply capa	city[kVA]	0.3	0.4	0.7	1.3	2.4	3.5	0.3	0.5	0.7	1.3	
g	Torque[%]		150		100		50	30	150		100		
Braking	DC injection braking		Starting freq	uency: 0.0 to	60.0Hz, Brakin	g time: 0.0 to	30.0s, Braking	level: 0 to 100)%		•		
Θ	Braking transistor		-		Built-in				-		Built-in		
App	olicable safety standard	s	UL508C, EN	l 61800-5-1:20	007				UL508C				
Enc	closure (IEC 60529)		IP20 (IEC 60	0529:1989) / L	IL open type (l	JL50)							
Cod	oling method		Natural cool	ing			Fan cooling		Natural cooling				
Wei	ight / Mass[kg(lbs)]		0.6(1.3)	0.6(1.3)	0.7(1.5)	0.9(2)	1.8(4)	2.5(5.5)	0.7(1.5)	0.7(1.5)	0.8(1.8)	1.3(2.9)	

^{*1} The load shall be reduced so that the continuous operating current is the rated current in parenthesis or less if the carrier frequency is set to 3kHz or above or ambient temperature exceeds 40°C (104°F).

EMC Filter Built-in Model

Specifications

■Three-phase 400V series

	Item					;	Specifications	•					
Inpu	ıt power source		Three-phase 400V										
Тур	е		FRNC2E-4E										
(FR	N C2E-	4E)	0002	0004	0005	0007	0011	0013	0018	0024	0030		
Nor	ninal applied mo	tor[kW]	0.4	0.75	1.5	2.2	4.0	5.5	7.5	11	15		
Nor	ninal applied mo	tor[HP]	1/2	1	2	3	5	7.5	10	15	20		
	Rated capacity	[kVA]	1.3	1.3 2.3 3.2 4.8 8.0 9.9 13 18 22									
sg	Rated voltage[\	V]	Three-phase	380 to 480V (Wi	th AVR)								
ratings	Rated current[A	۸](*1)	1.8(1.5)	3.1(2.5)	4.3(3.7)	6.3(5.5)	10.5(9.0)	13	18	24	30		
Output				Current for 1min		0.5s (If the rated curre	nt is in parenthesis)		I current for 1mi I current for 0.5s				
	Rated frequenc	y[Hz]	50, 60Hz										
	Phases, Voltag	e, Frequency	Three-phase,	380 to 480V, 50)/60Hz								
Input ratings	Voltage/Freque	ncy variations	Voltage: +10 to -15% (Voltage unbalance : 2% or less), Frequency: +5 to -5%										
t rat	Rated current[A]	(with DCR)	0.85	1.6	3.0	4.4	7.3	10.6	14.4	21.1	28.8		
ndu		(without DCR)	1.7	3.1	5.9	8.2	13.0	17.3	23.2	33.0	43.8		
	Required power sup	ply capacity[kVA]	0.6	1.1	2.0	2.9	4.9	7.4	10	15	20		
Б	Torque[%]		100		50	30		20					
Braking	DC injection bra	aking	Starting freque	ency: 0.0 to 60.0	OHz, Braking tim	e: 0.0 to 30.0s	Braking level: 0	to 100%					
m	Braking transis	tor	Built-in										
App	licable safety sta	andards	UL508C, EN	61800-5-1:2007									
(ĖŃ	licable EMC star 61800-3:2004 + progress)	ndards A1:2012)	Immunity : Se Emission : Ca	cond Environme tegory C2	ent (Industrial)			Immunity : Se Emission : Ca	cond Environmentegory C3	ent (Industrial)			
Enc	losure (IEC 6052	29)	IP20 (IEC 605	529:1989) / UL o	pen type (UL50)							
Coc	ling method		Natural coolin	g	Fan cooling								
Wei	ght / Mass[kg(lb	s)]	1.5(3.3)	1.6(3.5)	3.0(6.6)	3.1(6.8)	3.2(7.1)	4.6(10.1)	4.6(10.1)	6.7(15)	6.7(15)		

^{*1} The load shall be reduced so that the continuous operating current is the rated current in parenthesis or less if the carrier frequency is set to 3kHz or above or ambient temperature exceeds 40°C (104°F).

Single-phase 200V series

	Item				Specific	cations					
Inpu	ıt power source		Single-phase 200V								
Тур	е		FRN C2E-7E								
(FR	N C2E-	7E)	0001	0002	0004	0006	0010	0012			
Nor	ninal applied mo	tor[kW]	0.1	0.2	0.4	0.75	1.5	2.2			
Nor	ninal applied mo	tor[HP]	1/8	1/4	1/2	1	2	3			
	Rated capacity	[kVA]	0.30	0.57	1.3	2.0	3.5	4.5			
sge	Rated voltage[\	/]	Single-phase, 200 to 2	240V, 50/60Hz							
ratir	Rated current[A	\](*1)	0.8(0.7)	1.5(1.4)	3.5(2.5)	5.5(4.2)	9.2(7.0)	12.0(10.0)			
Output ratings	Overload capal	oility	150% of rated current 150% of rated current		ed current for 0.5s (If the	e rated current is in pare	enthesis)				
	Rated frequency[Hz] 50, 60Hz										
	Phases, Voltag	e, Frequency	Single-phase, 200 to 2	240V, 50/60Hz							
Input ratings	Voltage/Freque	ncy variations	Voltage: +10 to -10%,	Frequency: +5 to -5%							
ıt rat	Rated current[A]	(with DCR)	1.1	2.0	3.5	6.4	11.6	17.5			
lnpu		(without DCR)	1.8	3.3	5.4	9.7	16.4	24.0			
	Required power sup	ply capacity[kVA]	0.3	0.4	0.7	1.3	2.4	3.5			
l gc	Torque[%]		150		100		50	30			
Braking	DC injection bra	aking	Starting frequency: 0.0	0 to 60.0Hz, Braking tim	e: 0.0 to 30.0s, Braking	level: 0 to 100%					
В	Braking transis	tor	_		Built-in						
App	licable safety sta	andards	UL508C, EN 61800-5	-1:2007							
(ĖN	licable EMC star 61800-3:2004 + progress)		Immunity : Second En Emission : Category C								
Enc	losure (IEC 605	29)	IP20 (IEC 60529:1989	9) / UL open type (UL50))						
Coc	ling method		Natural cooling				Fan cooling				
Wei	ght / Mass[kg(lb	s)]	0.7(1.5)	0.7(1.5)	0.8(1.8)	1.2(2.6)	3.0(6.6)	3.0(6.6)			

^{*1} The load shall be reduced so that the continuous operating current is the rated current in parenthesis or less if the carrier frequency is set to 3kHz or above or ambient temperature exceeds 40°C (104°F).

Common Specifications

Common Specifications

	Item	Explanation	Remarks					
	Maximum frequency	25 to 400Hz						
1	Base frequency	25 to 400Hz						
and	Starting frequency	0.1 to 60.0Hz						
Setting range	Carrier frequency	0.75 to 16kHz Note: The unit is equipped with an automatic reduction/stop function that may automatically drop the carrier frequency to protect the inverter when it is running at frequencies above 6 kHz, depending on ambient temperature, output current, and other conditions. (*1) • Under modulated carrier conditions, the system scatters carrier frequency to reduce noise						
A	Accuracy (stability)	· Analog setting: : Absolute accuracy within ± 2% (at 25°C(77°F)), temperature drift within ± 0.2% (25°C(77°F) ± 10°C(50°F)) · Keypad setting: : Absolute accuracy within ± 0.01% (at 25°C(77°F)), temperature drift within ± 0.01% (25°C(77°F) ± 10°C(50°F)						
S	Setting resolution	- Analog setting : 1/1000 of maximum frequency - Keypad setting : 0.01Hz (99.99Hz or less), 0.1Hz (100.0Hz to 400.0Hz) - Link operation : 1/20000 of maximum frequency or 0.01Hz (fixed)						
С	Control method	Induction motor drive · V/f control · Slip compensation · Automatic torque boost · Dynamic torque vector control · Automatic energy-saving function						
		Synchronous motor drive · Sensorless magnetic positioning (speed control range: 10% of base frequency and up)						
		Base frequency and maximum output frequency can each be set between :80 to 240 200V series AVR control (*1) can be turned ON or OFF All purples and frequency (%) cartiage (%) cartiage (%) and frequency (%) (%) and frequency (%) (%) (%) (%) (%) (%) (%) (%) (%) (%)						
'	Voltage/freq. characteristic	Allowable non-linear V/f (*1) settings (2): optional voltage (0–240V) and frequency (0–400Hz) Base frequency and maximum output frequency can each be set between :160 to 500 AVR control (*1) can be turned ON or OFF Allowable non-linear V/f (*1) settings (2): optional voltage (0–500V) and frequency (0–400Hz)						
r		· Automatic torque boost (for constant torque loads)						
Т	Forque boost (*1)	· Manual torque boost: Optional torque boost value can be set between 0.0 and 20.0%						
		· Application load can be selected (for constant and variable torque loads)						
S	Starting torque (*1)	150% or more/frequency set to 3Hz Slip compensation /automatic torque boost active						
		Keypad operation : Start and stop with RUN, STOP keys (standard keypad) : Start and stop with RUN, STOP keys (remote keypad: optional)						
S	Start/stop	External signals : FWD (REV) operation/stop command [3-wire operation enabled] (digital input) Coast-to-stop command, trip command (external fault), fault reset, etc.						
		Link operation : Communication via RS-485						
		Changing run command: Communications used to change run command						
		Keypad operation : Can be set with or key (with save data function) Also can be set with function code (only via communication) and be copied.(*2)						
		Set based on built-in volume						
		Analog input : 0 to +10V DC/0 to 100% (terminal 12) : 4 to +20mA DC/0 to 100%, 0 to +20mA DC/0 to 100% (terminal C1)						
F	requency setting	Multistep frequency : Selectable from 16 steps (step 0 to 15)						
ľ	- 4,	UP/DOWN operation : Raises or lowers frequency while digital input signal is ON						
		Link operation: : Frequency set through RS-485 communication						
		Changing frequency settings : Two types of frequency settings can be changed using external signals (digital input) : frequency settings and multistep frequency settings						
		Auxiliary frequency setting: Built-in potentiometer, Inputs at terminal 12, C1 can be added to the main setting as auxiliary frequency setting.						
		Can be switched from (DC 0 to +10V/0 to 100%) to (DC +10 to 0V/0 to 100%) externally						
A	acceleration/deceleration time	Can be set between 0.00 and 3600s There are two independent settings that can be selected for acceleration/deceleration time (can be switched while running) Pattern: The following four acceleration/deceleration types can be selected Linear, S-curve (weak/strong), non-linear (constant output maximum capacity acceleration/deceleration) Coast-to-stop acceleration/deceleration is enabled when run commands are OFF Acceleration/deceleration time can be set during jogging operation (between 0.00 and 3600s)						

^{*1} Only valid when induction motor drive is in operation

Common Specifications

Common Specifications

	Item	Explanation	Remarks				
	Frequency limiter (Peak/bottom frequency limit)	High and low limiters can be set in addition to Hz values (0–400Hz)					
	Bias frequency	Bias of set frequency and PID command can be set separately between 0 and ±100%					
	Gain for frequency setting	Analog input gain can be set between 0 and 200%					
	Jump frequency control	Three operation points and their common jump hysteresis width can be set (0–30Hz) Six operation points and their common jump hysteresis width can be set (0–30Hz) (*2)					
	Timer operation	Operation starts and stops at the time set from keypad (1 cycle)					
	Jogging operation (*1)	Operated using the RUN key (on the standard or remote keypad) or digital contact point input (acceleration and deceleration timesame duration used only for jogging)					
	Auto-restart after momentary power failure (*1)	Trip at power failure: The inverter trips immediately after power failure. Trip at power recovery: Coast-to-stop at power failure and trip at power recovery Deceleration stop: Deceleration stop at power failure, and trip after stoppage (*2) Start at the frequency selected before momentary stop: Coast-to-stop at power failure and start after power recovery at the frequency selected before momentary stop. Start at starting frequency: Coast-to-stop at power failure and start at the starting frequency after power recovery.					
	Current limit by hardware (*1)	Uses hardware to limit current and prevent overcurrent trips resulting from sudden load changes, momentary power failures, and similar events that cannot be handled by software current limiters (can be canceled)					
Control	Slip compensation (*1)	Compensates for decrease in speed according to the load, enabling stable operation					
Š	Current limit	Keeps the current under the preset value during operation					
	PID control	Process PID regulator PID command, keyboard, analog input (terminal 12, C1), RS-485 communication Feedback value: Analog input (terminal 12, C1) Low liquid level stop function Switch forward/reverse operation Integration reset/hold function					
	Automatic deceleration	- Automatically limits output frequency, limits energy generated by the inverter, and avoids overcurrent trips when torque relay value is exceeded (*1) - Makes deceleration time three times longer to avoid "" trip when DC link circuit voltage exceeds overage limit					
	Deceleration characteristics (improved braking capacity)	Increases motor loss and reduces energy generated by the inverter during deceleration to avoid overcurrent trips					
	Energy saving operation (*1)	Restricts output voltage to minimize total motor and inverter loss during constant speed operation					
	Overload prevention control	Lowers frequency when IGBT junction temperature and ambient temperature rise due to overloading to avoid further overload					
	Offline tuning (*1)	Performs r1, $X\sigma$, and excitation current tuning Performs r1, $X\sigma$, slip frequency and excitation current tuning (*2)					
	Fan stop operation	Detects inverter internal temperature and stops cooling fan when the temperature is low					
	Secondary motor settings	 Switching between two motors in the same inverter is enabled (switching cannot be performed while the inverter is running) Induction motor settings can only be applied to the second motor Data settings (base frequency, rated current, torque boost, electronic thermal, and slip compensation, etc.) can be entered for the second motor Constants can be set within the second motor. Auto-tuning is also enabled. 					
	Rotational direction limits	Select either prevent reverse or prevent forward operation					
	Running/stopping	Speed monitor, output current [A], output voltage [V], input power [kW], PID reference, PID feedback value, PID output, timer value (for timer operation) [s], total power amount Select the speed monitor to be displayed from the following: Output frequency (before slip compensation) [Hz], output frequency (after slip compensation) [Hz], set frequency [Hz], load shaft speed [min ⁻¹], line speed [m/min], constant rate of feeding time [min]					
	Lifetime alarm	Displays the lifetime alarm for the main circuit condenser, PCB condenser, and cooling fan. External output is enabled for lifetime alarm information.					
	Total running time	Can display total motor running time, total inverter running time, and total power use					
	I/O check	Displays control circuit terminal output status					
_	Energy saving monitor	Power consumption, power consumption x coefficient					
Indication	Trip mode	Displays cause of trip: □□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□					
	Running or Trip mode	Trip history: Saves and displays the last 4 trip codes and their detailed description Saves and displays detailed data for each section on up to four past trips					

^{*1} Only valid when induction motor drive is in operation

^{*2} These functions can be supported by the inverters having a ROM version 0500 or later

Common Specifications

C	Ol	mmon Speci	rications								
		Item		Explanation	Remarks						
	0	vercurrent	Stops the inverter t	o protect against overcurrent due to overload	LED display						
	SI	hort-circuit	Stops the inverter t	o protect against overcurrent due to a short circuit in the output circuit	OC1 OC2						
	G	iround fault	Stops the inverter t	o protect against overcurrent due to a ground fault (initial ground circuit only) in the output circuit	OC3						
	0	vervoltage		tage in DC link circuit (200V: DC 400V,400V: DC 800V) and stops the inverter inst significantly large voltage input mistakenly applied	OU1 OU2 OU3						
	Ur	ndervoltage		link circuit voltage (200V: DC 200V,400V: DC400V) and stops the inverter will sound if auto-restart after momentary power failure is selected							
	In	put phase loss	Stops or protects the inverter against input phase loss Even when there is input phase loss, the loss may not be detected if the connected load is light or a DC reactor is connected to the inverter								
	Οι	utput phase loss detected	Detects loss from breaks in output wiring while running or during startup and stops the inverter								
	_		Stops the inverter by d	etecting the temperature of the inverter cooling system (e.g. when the cooling fan is malfunctioning or there is an overload)	OH1						
	O	verheating	Protects against ov	erheating during braking resistance based on braking resistor electronic thermal function settings	dbH						
	O	verload	Stops the inverter ba	ased on the temperature of the cooling system and the switching element calculated from output current flow	OLU						
	E>	xternal alarm input	Stops the inverter a	larm through digital input (THR)	OH2						
	protection	Electronic thermal	Protects the standa	nverter to protect the motor according to electronic thermal function settings rd motor and inverter motor over the full frequency range. The second motor can also be on level and thermal time constant can be set between 0.5 and 75.0 minutes)	OL1 OL2						
	Motor pr	PTC thermistor	-	Stops running the inverter to protect the motor when the PTC thermistor detects motor temperature A PTC thermistor is connected between terminals C1 and 11, and a resistor is connected between terminals 13 and C1. Set function code.							
_		Overload early warning	Outputs a prelimina	ry alarm at a preset level before the electronic thermal stops the inverter	_						
ction	М	lemory error	Checks data when	the power is turned on and data is being written, and stops the inverter if a memory malfunction is detected.	Er1						
Protection				f a communication malfunction is detected between the keypad and inverter unit while an operation gress from the remote keypad							
	С	:PU error	Stops the inverter if	a CPU malfunction caused by noise or similar factors is detected	Er3						
	0	operation error	Start check	Pressing the stop key on the keypad forces the inverter to stop, even if run commands are being delivered via terminals or communications. Er6 is displayed once stop is complete. Prohibits run operations and displays Er6 if a run command is given while any of the following status changes are occurring: Powering up · Canceling an alarm	Er6						
			Stops the inverter when there is a tuning failure, interruption, or abnormality in tuning results during motor constant tuning								
-		uning error (*1)	-		Er7						
-		S-485 communication error	<u> </u>	a communications malfunction is detected in RS-485 communication with the inverter unit	Er8						
-		ta save error during undervoltage		data save cannot proceed normally because an undervoltage protection function is activated	ErF Erd						
		tep out detected (*2)		Stops the inverter when a synchronous motor step out is detected							
		ID feedback break detected	· ·	nen a break is detected during current input (C1 terminal) distribution to PID feedback (can be enabled/disabled)	CoF						
	St	tall prevention		uced to avoid an overcurrent trip when output current exceeds the limit during acceleration/deceleration or constant speed operation							
	Al	larm output (for any fault)		gnal when the inverter is stopped due to an alarm can be canceled by pressing the PRG/RESET key or by inputting a digital signal (RST)							
	R	Retry	Inverter can be auton	natically reset and restarted after stopping due to a trip (the number of retries and wait time until reset can also be set)							
	In	ncoming surge	Protects the inverte	r from surge voltage between the main circuit and ground terminal							
	М	Iomentary power failure	•	ctive function (stops the inverter) when there is a momentary power failure of 15ms or more ores voltage within the set time when momentary power failure restart is selected							
	M	lock malfunction	Can output a mock	alarm to check malfunction sequences	Err						
	In	stallation location	Must be indoors aKeep out of direct	nd free of corrosive gases, flammable gases, dust, and oil mist (contamination level 2 (IEC 60664-1: 2007) sunlight							
	Aı	mbient temperature	Open: -10°C (14°F) to + 50°C (122°F) (IP20)							
nt	Aı	mbient humidity	5 to 95%RH (no co	ndensation)							
Environment	AI	ltitude	Above 1000m (330 Above 1000m (330	ess (Output derating is not necessary.) Off) to 3000m (9800ft) or less (Output derating is necessary.) Off) to 1500m (4900ft) or lower: 0.97, Above 1500m (4900ft) to 2000m (6600ft) or lower: 0.95, Off) to 2500m (8200ft) or lower: 0.91, Above 2500m (8200ft) to 3000m (9800ft) lower: 0.88							
	Vi	ibration	3mm (0.12inch) (vibra	ation width): 2 to less than 9Hz, 9.8m/s²: 9 to less than 20Hz, 2m/s²: 20 to less than 55Hz, 1m/s²: 55 to less than 200Hz							
	Sa	aved temperature	-25°C (77°F) ± 70°0	C (158°F)							
	Sa	aved humidity	5 to 95%RH (no co	ndensation)							

^{*1} Only valid when induction motor drive is in operation

^{*2} These functions can be supported by the inverters having a ROM version 0500 or later

Terminal Functions

Terminal Functions

Category	Symbol	Terminal Name	Functions	Remarks
	L1/R,L2/S,L3/T	Power input	Connect a three-phase power supply (three-phase 200V,400V)	
Main circuit	U,V,W	Inverter output	Connect a three-phase induction motor	
	P(+) ,P1	For DC REACTOR	Connect the DC REACTOR	
n cir	P(+) ,N(-)	For DC bus connection	Used for DC bus connection system	
Ma	P(+) ,DB	For EXTERNAL BRAKING RESISTOR	Connect external braking resistor	Only for 0.4kW and above. Connections are enabled for 0.2kW and below, but operation will not work.
	●G(2-terminal)	Grounding	Ground terminal for inverter chassis	
	13	Potentiometer power supply	Power supply for frequency setting potentiometer (1 to $5k\Omega)$	DC10V
		Voltage input	· Used as voltage input for frequency setting 0 to +10V DC/0 to 100%	
setting	12	(Inverse operation) (PID control) (Frequency aux. setting)	+10 to +0V DC/0 to 100% Used for reference signal (PID process command) or feedback signal Used as additional auxiliary setting to various main settings of frequency	
Frequency setting		Current input	· Used as current input for frequency setting +4 to +20mA DC (0 to +20mA DC)/0 to 100%	
Fre	C1	(Inverse operation) (PID control) (Frequency aux. setting)	+4 to +20mA DC (0 to +20mA DC)/0 to 100% Used for reference signal (PID process command) or feedback signal Used as additional auxiliary setting to various main settings of frequency	
		(For PTC thermistor)	· Connects PTC thermistor for motor protection	
	11(2-terminal)	Common	Common terminal for frequency setting signal (12, 13, C1, FMA)	Isolated from terminal CM and Y1E
	X1 Digital input 1		The following functions can be set at terminals X1 to X3, FWD,	
-	X2 Digital input 2		and REV for signal input Common function	
	X3	Digital input 3	· Switch between synch/source using the built-in switches on the unit	
	FWD Forward operation co		Short-circuit ON or open circuit ON settings are enabled between the terminal X1 and CM The second till a local CM and CM and CM and CM and CM are CM and CM	
	REV Reverse operation command		The same setting is possible between CM and any of the terminals among X2, X3, FWD, and REV.	
	(FWD) Forward operation command		The motor runs in the forward direction when (FWD) is ON, stops after deceleration when FWD is OFF	Only terminal FWD/REV settings are allowed, only short circuit ON
	(REV)	Reverse operation command	The motor runs in the reverse direction when (REV) is ON, stops after deceleration when REV is OFF	do.
Digital input	(SS1) (SS2) (SS4) (SS8) (SS8) Multistep freq. selection		16-speed operation is enabled using the ON/OFF signal from (SS1) through (SS8) Frequency	
Digita	(RT1)	ACC/DEC selection	Acceleration/deceleration time setting 1 is active when RT1 is OFF Acceleration/deceleration time setting 2 is active when RT1 is ON	
	(HLD)	3-wire operation stop command	Used as an automatic hold signal during 3-wire operation The FWD or REV signal is automatically stopped when HLD is ON, and the hold is removed when HLD is OFF	
	(BX) Coast-to-stop command		When BX is ON, inverter output is shut off immediately and the motor coasts-to-stop (no alarm output)	
	(RST) Alarm reset		Alarm hold status is removed when RST is ON	Signal at 0.1s or higher
	(THR)	Trip command (External fault)	When THR is OFF, inverter output is shut off immediately and the motor coasts-to-stop (alarm output enabled: OH2)	
	(JOG)	Jogging operation	Turn JOG ON to enable jogging operation: switches the running mode to jogging mode, the frequency setting to jogging frequency, and acceleration/deceleration time to jogging running use	(*1)
	(Hz2/Hz1)	Freq. set 2/ Freq. set 1	Frequency setting 2 is selected when Hz2/Hz1 is ON	
	(M2/M1)	Motor 2/Motor 1	Motor 1 settings take effect when M2/M1 is OFF. Motor 2 settings take effect when M2/M1 is ON.	

 $^{^{\}star}1$ Only valid when induction motor drive is in operation

ategory	Symbol	Terminal Name	Functions	Remarks
	(DCBRK)	DC brake command	Turn DCBRK ON to start direct current braking	
	(WE-KP)	Write enable for KEYPAD	Function code data changes can only be made when the keypad is turned ON with WE-KP	
	(UP)	UP command	Output frequency increases while UP is ON	
put	(DOWN)	DOWN command	Output frequency decreases while DOWN is ON	
	(Hz/PID)	PID control cancel	PID control is canceled when Hz/PID is ON (runs based on multistep frequency/keypad/analog input etc.)	
Digital input	(IVS)	Inverse mode changeover	Switch from analog frequency setting or PID control output signal (frequency setting) operation mode to forward/reverse operation. Reverse operation enabled when IVS is ON.	
	(LE)	Link enable (RS485, Bus)	Operates according to commands from RS-485 when LE is ON	
	(PID-RST)	PID integral/differential reset	Turn PID-RST ON to reset PID integration and differential values	
	(PID-HLD)	PID integral hold	Turn PID-HLD ON to hold PID differentiation	
	PLC	PLC terminal	Connect to PLC output signal power supply Common for 24V power	+24V (22–27V) Max 50mA
	CM(2-terminal)	Common	Common for digital input signal	Isolated from terminal 11 and Y1E
	(PLC)	Transistor output power	Power supply for transistor output load (Max: DC 24V DC 50mA) (Caution: Same terminal as digital input PLC terminal)	Short circuit between terminal Cland Y1E is used
	Y1	Transistor output	Select one of the following signals for output: Short circuit when ON signal is output or open circuit when ON signal is output	Max. voltage: 27Vdc, max. current: 50mA, leak current: 0.1mA max., ON voltage: within 2V(at 50m
	(RUN)	Inverter running (speed exists)	Comes ON when the output frequency is higher than starting frequency	
	(FAR) Speed/freq. arrival		Comes ON when the difference between output frequency and set frequency rises above the frequency arrival detection range (function code E30)	
	(FDT) Speed/freq. detection		Comes ON when output frequency falls below operational level (function code E31). Turns OFF when it falls below operational level (function code E31) or hysteresis width (function code E32).	
	(LU)	Undervoltage detection	Comes ON when there is a run command and running has stopped due to insufficient voltage	
	(IOL)	Inverter output limit	Comes ON when the inverter is experiencing limited current, automatic deceleration, or limited torque operation	
	(IPF)	Auto-restarting	Comes ON during auto restart operation (after momentary power failure and until completion of restart).	
ıtbnt	(OL)	Overload early warning	Comes ON when the electronic thermal relay value is higher than the preset alarm level	
Transistor output	(SWM2)	Switch to Motor 2	Comes ON when Motor 2 is selected by inputting a motor switch signal (M2/M1)	
Tran	(TRY)	Auto-resetting mode	Comes ON during auto reset mode	
	(LIFE)	Lifetime alarm	Alarm signal is output according to lifetime assessment standards inside the inverter	
	(PID-CTL)	PID control in progress	Comes ON when PID control is in effect	
	(PID-STP)	PID low water volume stop in progress	Comes ON when low liquid level stop is in effect in PID control (also stops based on the status of input run command)	
	(RUN2)	Inverter output in progress	Comes ON when the inverter is running above startup frequency and DC braking is also in operation (Comes ON when the inverter main circuit (gate) is ON)	
	(OLP)	Overload preventive control	Comes ON when overload prevention control is operating	
	(ID2)	Current detection 2	Comes ON when a current larger than the set value (for ID2) is continuously detected for longer than the time set on the timer	
	(THM)	Thermistor detected	Comes ON when motor overheating is detected by the PTC/NTC thermistor	(*1)
	(BRKS)	Brake signal	Outputs a brake engage/release signal	(*1)
	(MNT)	Maintenance timer	Alarm signal is generated when time passes or start-up exceeds over the preset value	(*2)
	(FARFDT)	Frequency arrival/frequency detected	Comes ON when both (FAR) and (FDT) are ON	
	(C1OFF)	C1 terminal break detected	Comes ON when the system determines that a break will occur if terminal C1 input falls below 2mA	
	(ID)	Current detection	Comes ON when a current larger than the set value has been detected for the timer-set time	

^{*1} Only valid when induction motor drive is in operation

^{*2} These functions can be supported by the inverters having a ROM version 0500 or later

Terminal Functions

Terminal Functions

Category	Symbol	Terminal Name	Functions	Remarks
	Syllibol	reminal Name	Functions	Remarks
Transistor output	(IDL)	Small current detection	Comes ON when a current smaller than the set value has been detected for the timer-set time	
nsist	(ALM)	Alarm relay (for any fault)	Alarm signal is output as the transistor output signal	
Trai	Y1E	Transistor output common	Common terminal for transistor output	Isolated from terminal 11 and CM
Relay output	30A, 30B, 30C	Alarm relay output (for any fault)	Outputs a no-voltage contact signal (1c) when the inverter stops the alarm Can select the same signal as the Y1 signal for multipurpose relay output Can switch between alarm output through excitation operation and alarm output through non-excitation operation	Contact rating : AC250V, 0.3A, cosφ=0.3 DC48V, 0.5A
Analog output	FMA	Analog monitor	Output format: DC voltage (0–10V) Output can be performed in one of the following selected analog formats Output frequency 1 (Before slip compensation) Output frequency 2 (After slip compensation) Output current Output voltage Input power PID feedback value DC link circuit voltage Analog output test PID command PID output	Gain setting between 0 and 300%
LINK		Built-in RJ-45 connector (RS-485 communication)	Any of the following protocols can be selected: Dedicated keypad protocol (automatically selected) Modbus RTU Fuji dedicated inverter protocol SX protocol (for PC loader)	Provides power to the keypad Includes terminator ON/OFF switch Communication data storage can be selected.(*2)

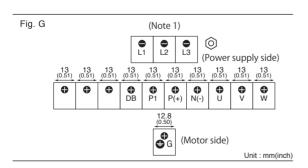
^{*2} These functions can be supported by the inverters having a ROM version 0500 or later

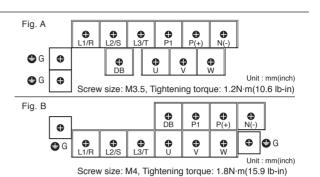
Terminal Functions

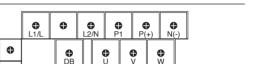
Terminal Arrangement

Main circuit terminals

Power source	Nominal Applied Motor (kW(HP))	Inverter Type	Reference				
	0.1 (1/8)	FRN0001C2S-2□					
	0.2 (1/4)	FRN0002C2S-2□	Fig. A				
	0.4 (1/2)	FRN0004C2S-2□	I Ig. A				
	0.75 (1)	FRN0006C2S-2□					
Three-phase	1.5 (2)	FRN0010C2S-2□					
200V	2.2 (3)	FRN0012C2S-2□	Fig. B				
200 V	3.7 (5)	FRN0020C2S-2□					
	5.5(7.5)	FRN0025C2S-2□	Fig. E				
	7.5(10)	FRN0033C2S-2□	i ig. L				
	11(15)	FRN0047C2S-2□	Fig. F				
	15(20)	FRN0060C2S-2□	1 ig. i				
	0.4 (1/2)	FRN0002C2□-4□					
	0.75 (1)	,					
	1.5 (2)	Fig. B					
	2.2 (3)	FRN0007C2□-4□					
	3.7 (5)	FRN0011C2□-4□					
Thuas ubass	5.5(7.5)	FRN0013C2S-4□	Fig. E				
Three-phase 400V	7.5(10)	FRN0018C2S-4□					
400 V	11(15)	FRN0024C2S-4□	Fig. F				
	15(20)	FRN0030C2S-4□	1 ig. i				
	5.5(7.5)	FRN0013C2E-4E	Fig. G				
	7.5(10)	FRN0018C2E-4E	i ig. d				
	11(15)	FRN0024C2E-4E	Fig. H				
	15(20)	FRN0030C2E-4E	- 1 ig. 11				
	0.1 (1/8)	FRN0001C2□-7□					
	0.2 (1/4)	FRN0002C2□-7□	Fig. C				
Single-phase	0.4 (1/2)	FRN0004C2□-7□	Fig. C				
200V	0.75 (1)	FRN0006C2□-7□					
	1.5 (2)	FRN0010C2□-7□	F:- D				
	2.2 (3)	FRN0012C2□-7□	Fig. D				
	0.1 (1/8)	FRN0001C2S-6U					
Single-phase	0.2 (1/4)	FRN0002C2S-6U	Fig. C				
100V	0.4 (1/2)	FRN0003C2S-6U	Fig. C				
	0.75 (1)	FRN0005C2S-6U					







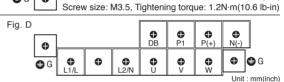
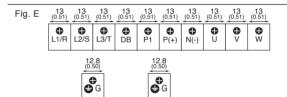


Fig. C

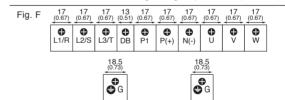
⊕ G

⊕G **⊕**

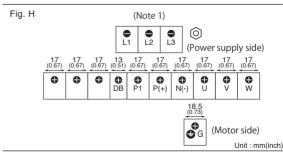
Screw size: M4, Tightening torque: 1.8N·m(15.9 lb-in)



Unit : mm(inch)
Screw size: M5, Tightening torque: 3.0N·m(26.6 lb-in)



Screw size: M6, Tightening torque: 5.8N·m(51.3 lb-in)



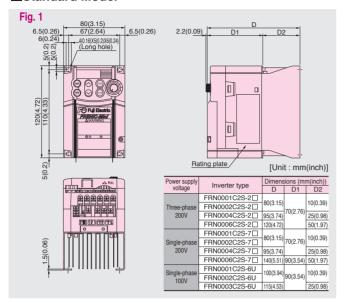
Control Circuit Terminals

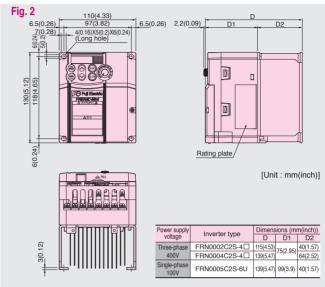


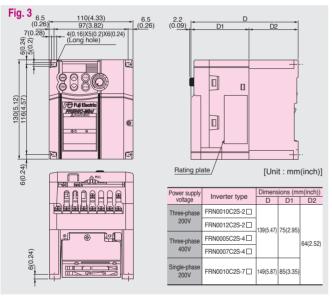
Screw size: M2.5, Tightening torque: 0.4N·m(3.5 lb-in)

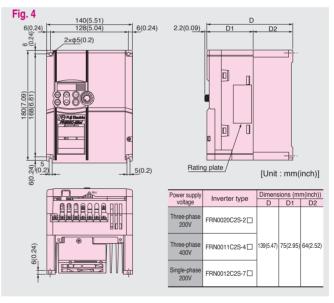
External Dimensions

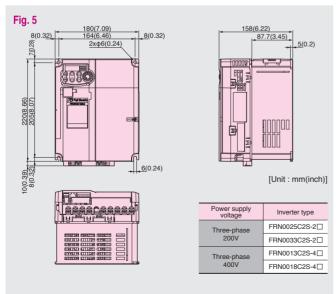
Standard Model

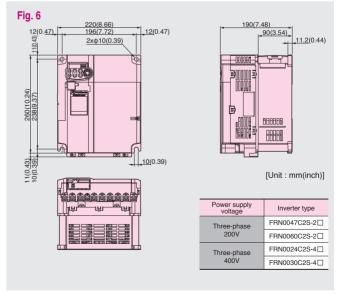




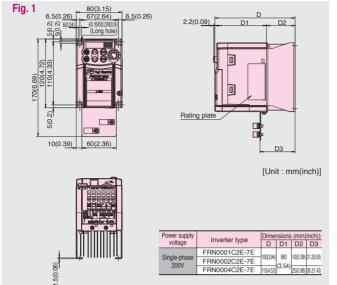


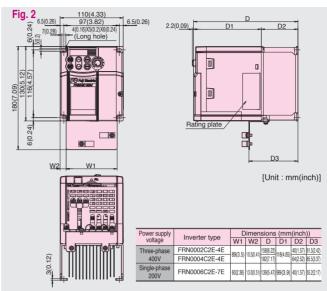


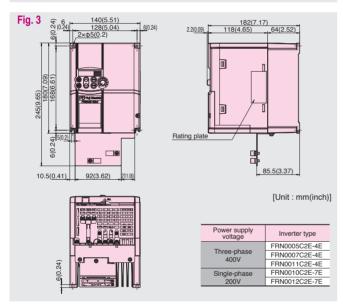


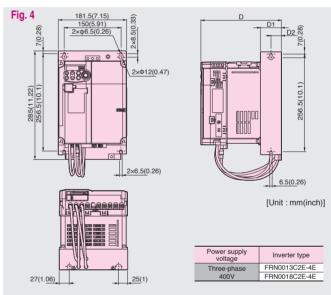


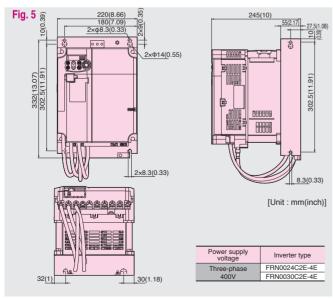
■EMC Filter Built-in Model



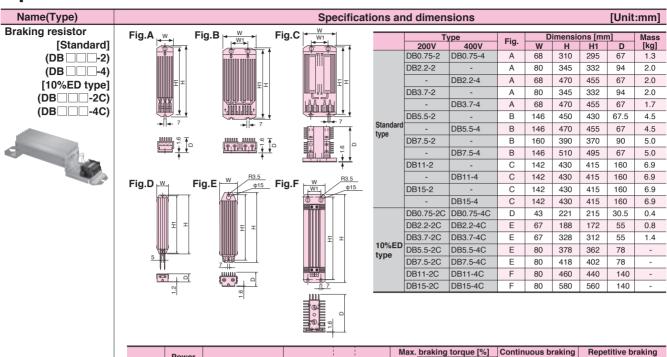








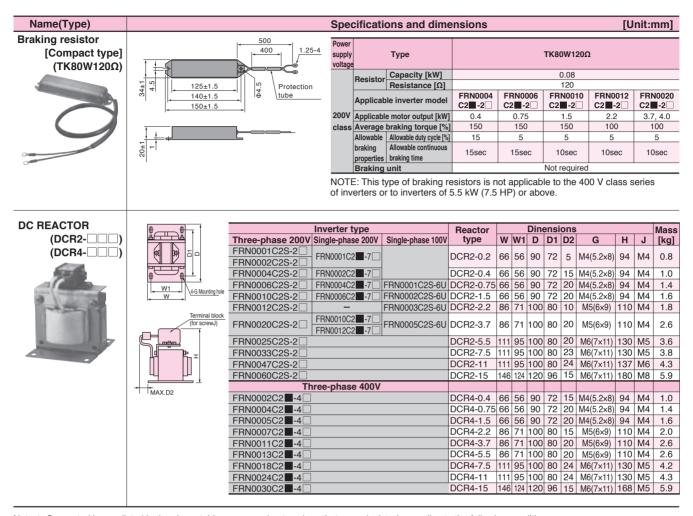
Options



	Power					Max.	braking to			us braking	Repetitive	
Type	supply	Inverter type	Туре	Q'tv	Resistance		50 [Hz]	60 [Hz]			(100 sec or	
,,	voltage		.,,,,		[Ω]		[N·m]	[N·m]	Discharging capability [kWs]	Braking time [s]	Average loss [kW]	[%ED]
		FRN0004C2S-2	DB0.75-2	1	100		4.02	3.32	9	45	0.044	22
		FRN0006C2S-2	DD0.70 Z	<u> </u>	100		7.57	6.25	17		0.068	18
	Three- phase 200 V	FRN0010C2S-2	DB2.2-2	1	40		15.0	12.4	34		0.075	10
		FRN0012C2S-2		į.			22.0	18.2	33	30	0.077	7
		FRN0020C2S-2	DB3.7-2	1	33	150	37.1	30.5	37	20	0.093	
		FRN0025C2S-2	DB5.5-2	1	20		55.1	45.4	55	20	0.138	
		FRN0033C2S-2	DB7.5-2	1	15		75.1	61.9	37		0.188	5
Standard		FRN0047C2S-2	DB11-2	1	10		110.2	90.8	55	10	0.275	
		FRN0060C2S-2	DB15-2	1	8.6		150.3	123.8	75		0.375	
		FRN0002C2■-4□	DB0.75-4	1	200		4.02	3.32	9		0.044	22
		FRN0004C2■-4□	DD0.73-4	1 '	200		7.57	6.25	17	45	0.068	18
Type		FRN0005C2■-4□	DB2.2-4	1	160		15.0	12.4	34		0.075	10
Турс	Three-	FRN0007C2■-4□	DB2.2-4	1	160		22.0	18.2	33	30	0.077	7
	phase	FRN0011C2■-4□	DB3.7-4	1	130	150	37.1	30.5	37	00	0.093	
	400 V	FRN0013C2 -4	DB5.5-4	1	80		55.1	45.4	55	10	0.138	
		FRN0018C2 -4	DB7.5-4	1	60		75.1	61.9	38		0.188	5
		FRN0024C2 -4	DB11-4	1	40		110.2	90.8	55		0.275	1
		FRN0030C2■-4□	DB15-4	1	34.4		150.3	123.8	75		0.375	
	Single- phase 200 V	FRN0004C2■-7□	DD0 75 0		100		4.02	3.32	9	45	0.044	22
		FRN0006C2■-7□	DB0.75-2	1	100	450	7.57	6.25	17		0.068	18
		FRN0010C2 -7				150	15.0	12.4	34	1	0.075	10
		FRN0012C2 -7	DB2.2-2	1	40		22.0	18.2	33	30	0.077	7
		FRN0003C2S-6U		i	1	450	4.02	3.32	9		0.044	22
	100 V	FRN0005C2S-6U	DB0.75-2	1	100	150	7.57	6.25	17	45	0.068	18
		FRN0004C2S-2		1			4.02	3.32	50 250	250	0.075	37
		FRN0006C2S-2	DB0.75-2C	1	100		7.57	6.25				20
		FRN0010C2S-2		i			15.0	12.4		73 50	1/	14
	Three-	FRN0012C2S-2	DB2.2-2C	1	40		22.0	18.2	55		0.110	
	phase	FRN0020C2S-2	DB3.7-2C	1	33	150	37.1	30.5	140	75	0.185	1
	200 V	FRN0025C2S-2	DB5.5-2C	1	20		55.1	45.4	55	20	0.275	1
		FRN0033C2S-2	DB7.5-2C	1	15		75.1	61.9	37	20	0.375	10
		FRN0047C2S-2	DB11-2C	1	10		110.2	90.8	55	10	0.55	
		FRN0060C2S-2	DB15-2C	1	8.6		150.3	123.8	75	1 .0	0.75	
		FRN0002C2■-4		1	1		4.02	3.32		250		37
		FRN0004C2 -4	DB0.75-4C	1	200		7.57	6.25	50	133	0.075	20
10%ED		FRN0005C2 -4			:		15.0	12.4		73		14
Туре	Thuas	FRN0007C2 -4	DB2.2-4C	1	160		22.0	18.2	55	50	0.110	14
	Three- phase	FRN0011C2 -4	DB3.7-4C	1	130	150	37.1	30.5	140	75	0.185	1
	400 V	FRN0013C2 -4	DB5.5-4C	1	80	100	55.1	45.4	55	20	0.105	1
		FRN0018C2 -4	DB7.5-4C	1	60		75.1	61.9	38		0.275	10
		FRN0024C2 -4	DB11-4C	1	40		110.2	90.8	55	10	0.575	1
		FRN0030C2■-4	DB15-4C	1	34.4		150.3	123.8	75	1 10	0.75	1
		FRN0004C2 -7		!			4.02	3.32		250		37
	Single-	FRN0006C2 -7	DB0.75-2C	1	100		7.57	6.25	50	133	0.075	20
	phase	FRN0010C2 -7				150	15.0	12.4		73		14
	200 V	FRN0010C2 -7	DB2.2-2C	1	40		22.0	18.2	55	50	0.110	10
	Cingle phase	FRN0003C2S-6U		1			4.02	3.32		250		37
	Single-phase 100 V	FRN0005C2S-6U	DB0.75-2C	1	100	150	7.57	6.25	50	133	0.075	20
	100 4	11110003023-00	1	1	1		/.5/	0.25	1	133		1 20

Note: 1) A box (\Box) in the above table replaces A, C, E, or U depending on shipping destination.

²⁾ A box (■) in the above table replaces S (Basic type) or E (EMC filter built-in type) depending on the enclosure.



Note 1: Generated losses listed in the above table are approximate values that are calculated according to the following conditions:

- The power source is 3-phase 200 V/400 V 50 Hz with 0% interphase voltage unbalance ratio.
- The power source capacity uses the larger of either 500 kVA or 10 times the rated capacity of the inverter.
- The motor is a 4-pole standard model at full load (100%).
- An AC reactor (ACR) is not connected.

Note 2:A box (☐) in the above table replaces A, C, E, or U depending on shipping destination.

Note 3:A box (☐) in the above table replaces S (Basic type) or E (EMC filter built-in type) depending on the enclosure.

Options

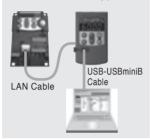
Remote keypad (TP-E1)

The keypad permits remote control of FRENIC-Mini, and function setting and display (with copy function).



■USB-equipped remote keypad (TP-E1U)

Using the keypad in combination with FRENIC Loader enables a variety of data about the inverter unit to be saved in the keypad memory, allowing you to check the information in any place.



■ Remote operation extension cable (CB-□S)

This straight cable is used to connect the RS485 Communications card and the remote keypad, and available in three lengths, i.e. 1m, 3m and 5m.



Туре	L(m)
CB-5S	5
CB-3S	3
CB-1S	1
	CB- S)

■ Mounting adapters (MA-C1-□□□)

FRENIC-Mini series of inverters can be installed in the control board of your system using mounting adapters which utilize the mounting holes used for conventional inverters (FVR-E11S series of 0.75 kW or below or 3.7 (4.0) kW). The FVR-E11S-2/4 (1.5 kW/2.2 kW) and FVR-E11S-7 (0.75 kW/1.5 kW) models may be replaced with the FRENIC-Mini series inverters without the use of adapters.

Ontion model	Applicable in	Applicable inverter model							
Option model	FRENIC-Mini	FVR-E11S							
	FRN0001C2S-2	FVR0.1E11S-2							
	FRN0002C2S-2	FVR0.2E11S-2							
	FRN0004C2S-2	FVR0.4E11S-2							
MA-C1-0.75	FRN0006C2S-2	FVR0.75E11S-2							
WIA-01-0.73	FRN0001C2S-7	FVR0.1E11S-7							
	FRN0002C2S-7	FVR0.2E11S-7							
	FRN0004C2S-7	FVR0.4E11S-7 □							
	FRN0006C2S-7								
	FRN0020C2S-2	FVR3.7E11S-2 □							
MA-C1-3 7	FRN0011C2S-4	FVR3.7E11S-4 □							
IVIA-01-3.7	FRN0012C2S-7	FVR4.0E11S-4							
		FVR2.2E11S-7 🗌							

Note: A box () in the above table replaces A, C, E, or U depending on shipping destination.

Rail mounting bases (RMA-C1-

A rail mounting base allows any of the FRENIC-Mini series of inverter to be mounted on a DIN rail (35 mm (1.38 inches) wide).

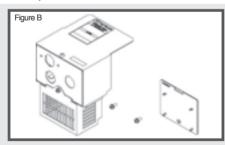
Option model	Applicable inverter type
	FRN0001C2S-2
	FRN0002C2S-2
	FRN0004C2S-2
	FRN0006C2S-2
RMA-C1-0.75	FRN0001C2S-7
	FRN0002C2S-7
1	FRN0004C2S-7
4	FRN0006C2S-7
1 10 1	FRN0001C2S-6U
7.7	FRN0002C2S-6U
0/-	FRN0003C2S-6U
	FRN0001C2E-7
	FRN0002C2E-7
	FRN0004C2E-7
	FRN0010C2S-2
	FRN0012C2S-2
RMA-C1-2.2	FRN0002C2S-4
	FRN0004C2S-4
	FRN0005C2S-4
A. Carrier	FRN0007C2S-4
	FRN0010C2S-7
200	FRN0002C2E-4
	FRN0004C2E-4
	FRN0006C2E-7
RMA-C1-3.7	FRN0020C2S-2
NIVIA-C1-3.7	FRN0011C2S-4
	FRN0012C2S-7
	FRN0005C2E-4
	FRN0007C2E-4
X	FRN0011C2E-4
4.	FRN0010C2E-7
	FRN0012C2E-7

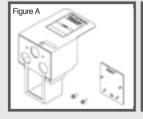
Note 1: A box (☐) in the above table replaces A, C, E, or U depending on shipping destination.

Note 2: This rail mounting base is not suitable for the inverters of 5.5 kW (7.5 HP) or above

■ NEMA1 kit (NEMA1-□□□C2-□)

Mounting the NEMA1 kit on the FRENIC-Mini series of inverters brings the inverter's enclosure into compliance with the NEMA1 Standard (UL TYPE1 certified).







Power supply voltage	Inverter type	Option type	Figure	
	FRN0001C2S-2	NEMA1-C2-101		
	FRN0002C2S-2		Α	
Three-phase	FRN0004C2S-2	NEMA1-C2-102		
200 V	FRN0006C2S-2	NEMA1-C2-103		
	FRN0010C2S-2	NEMA1-C2-201	В	
	FRN0012C2S-2	INCIVIAT-02-201		
	FRN0020C2S-2	NEMA1-C2-301	С	
	FRN0002C2S-4	NEMA1-C2-202	Α	
Three-phase	FRN0004C2S-4	NEMA1-C2-203		
400 V	FRN0005C2S-4	NEMA1-C2-201	В	
	FRN0007C2S-4	INCIVIAT-02-201		
	FRN0011C2S-4	NEMA1-C2-301	С	
	FRN0001C2S-7	NEMA1-C2-101	- A	
	FRN0002C2S-7	INCIVIA 1-02-101		
Single-phase	FRN0004C2S-7	NEMA1-C2-102		
200 V	FRN0006C2S-7	NEMA1-C2-104		
	FRN0010C2S-7	NEMA1-C2-204	В	
	FRN0012C2S-7	NEMA1-C2-301	С	
	FRN0001C2S-6U	NEMA1-C2-105		
Single-phase	FRN0002C2S-6U	INEINIA 1-02-105	Α	
100 V	FRN0003C2S-6U	NEMA1-C2-106	A	
	FRN0005C2S-6U	NEMA1-C2-205		

This option is not applicable to the EMC filter built-in type or inverters of 5.5 kW or above.

Wiring equipment

	Applicable motor rating [kW]		MCCB, ELCB Rated current [A]		Magnetic contactor type MC1 (for input circuit)		Magnetic	Recommended wire size (mm2) at 50°C (122°F) or below				
Power supply voltage		ing Inverter type	DC reactor (DCR)		DC reactor (DCR)		type MC2 (for output	Main circuit power input [L1/R , L2/S , L3/T] or [L1/L, L2/N]		Inverter output	DC reactor	Braking resistor
· · · · · · · · · · · · · · · · · · · ·			w/ DCR	w/o DCR	w/ DCR	w/o DCR	circuit)	w/ DC reactor (DCR)	w/o DC reactor (DCR)	[U, V, W]	[P1, P(+)]	[P(+), DB]
	0.1	FRN0001C2S-2	5 (6)	5 (6)	SC-05	SC-05	SC-05	2.0 (2.5)	2.0 (2.5)	2.0 (2.5)	2.0(2.5)	-
	0.2	FRN0002C2S-2										0.0 (0.5)
Three-phase	0.4	FRN0004C2S-2		10								2.0 (2.5)
	1.5	FRN0010C2S-2	10	15 (16)								
	2.2	FRN0010C2S-2	10	20 (25)								
200 V	3.7	FRN0020C2S-2	20 (25)	30 (35)		SC-5-1			5.5 (6)	3.5 (4)	3.5 (4.0)	
200 •	5.5	FRN0025C2S-2	30 (35)	50	SC-4-0	SC-5-1	SC-4-0	5.5 (6)	8 (10)	5.5 (6)	5.5 (6)	
	7.5	FRN0033C2S-2	40	75	SC-5-1	SC-N1	SC-5-1	8 (10)	14 (16)	8 (10)	14 (16)	
	11	FRN0047C2S-2	50	100	SC-N1	SC-N2S	SC-N1	14 (16)	22 (25)	14 (16)	22 (25)	
	15	FRN0060C2S-2	75	125	SC-N2	SC-N3	SC-N2	22 (25)	38 (50)	22 (25)	38 (50)	
	0.4	FRN0002C2 -4	5 (6)	5 (6)	SC-05	SC-05	SC-05	2.0 (2.5)	2.0 (2.5)	2.0 (2.5)	2.0 (2.5)	2.0 (2.5)
	0.75	FRN0004C2 -4										
	1.5	FRN0005C2 -4		10								
Three-	2.2	FRN0007C2 -4 -4 -FRN0011C2 -4 -4 -4 -4 -4 -4 -4 -4 -4 -4 -4 -4 -4	10	15 (16) 20 (25)								
phase 400 V	5.5	FRN0011C2 -4 -4 -	15 (16)	30 (35)					3.5 (4)			
400 V	7.5	FRN0018C2 -4	20 (25)	40		SC-4-0			5.5 (6)	3.5 (4)	3.5 (4)	
	11	FRN0024C2 -4	30 (35)	50	SC-4-0	SC-N1	SC-4-0	5.5 (6)	8 (10)	5.5 (6)	5.5 (6)	
	15	FRN0030C2 -4	40	60	SC-5-1	00 111	SC-5-1	8 (10)	14 (16)	8 (10)	14 (16)	
	0.1	FRN0001C2 -7	5 (6)	5 (6)	SC-05	SC-05	SC-05	2.0 (2.5)	2.0 (2.5)	2.0 (2.5)	2.0 (2.5)	-
Cimala	0.2	FRN0002C2 -7	(-)	- (-)				,	, ,	- (- /	- (- /	
Single- phase	0.4	FRN0004C2 -7		10								2.0 (2.5)
200 V	0.75	FRN0006C2 -7	10	15 (16)								
200 V	1.5	FRN0010C2 -7	15 (16)	20 (25)					3.5 (4.0)			
	2.2	FRN0012C2 -7	20 (25)	30 (35)		SC-5-1		3.5 (4.0)	5.5 (6.0)		3.5 (4.0)	
Single-	0.1	FRN0001C2S-6U	5 (6)	5 (6)	SC-05	SC-05	SC-05	2.0 (2.5)	2.0 (2.5)	2.0 (2.5)	-	-
phase	0.2	FRN0002C2S-6U	10	10								20(25)
100 V	0.4	FRN0003C2S-6U FRN0005C2S-6U	10	15 (16)					3.5 (4.0)			2.0 (2.5)
	0.75	FRINUUU3U23-6U	15 (16)	20 (25)					J.5 (4.U)			

Note) The symbol 🔳 is replaced with either of the following letters 🔳: S (Standard type), E (EMC filter built-in type)

•For molded-case circuit breakers (MCCB) and earth-leakage circuit breakers (ELCB), the required frame type and series depend on the facility transformer capacity and other factors. When selecting optimal breakers, refer to the relevant technical data. Also select the rated sensitive current of ELCB utilizing the technical data.

[•]The recommended wire sizes are based on the temperature inside the panel not exceeding 50°C.

[•]The above wires are 600V HIV insulated solid wires (75°C).

[•] Data in the above table may differ according to environmental conditions (ambient temperature, power supply voltage, and other factors).

COMPACT INVERTER FRENIC-Mini

MEMO

MEMO



When running general-purpose motors

Driving a 400V general-purpose motor

When driving a 400V general-purpose motor with an inverter using extremely long cables, damage to the insulation of the motor may occur. Use an output circuit filter (OFL) if necessary after checking with the motor manufacturer. Fuji's motors do not require the use of output circuit filters because of their reinforced insulation.

• Torque characteristics and temperature rise
When the inverter is used to run a general-purpose
motor, the temperature of the motor becomes
higher than when it is operated using a commercial
power supply. In the low-speed range, the cooling
effect will be weakened, so decrease the output
torque of the motor. If constant torque is required in
the low-speed range, use a Fuji inverter motor or a
motor equipped with an externally powered
ventilating fan

Vibration

When the motor is mounted to a machine, resonance may be caused by the natural frequencies, including that of the machine. Operation of a 2-pole motor at 60Hz or more may cause abnormal vibration.

- * Study use of tier coupling or dampening rubber.
- * It is also recommended to use the inverter jump frequencies control to avoid resonance points.

Noise

When an inverter is used with a general-purpose motor, the motor noise level is higher than that with a commercial power supply. To reduce noise, raise carrier frequency of the inverter. High-speed operation at 60Hz or more can also result in more noise.

When running special motors

Explosion-proof motors

When driving an explosion-proof motor with an inverter, use a combination of a motor and an inverter that has been approved in advance.

Brake motors

For motors equipped with parallel-connected brakes, their braking power must be supplied from the primary circuit (commercial power supply). If the brake power is connected to the inverter power output circuit (secondary circuit) by mistake, problems may occur.

Do not use inverters for driving motors equipped with series-connected brakes.

Geared motors

If the power transmission mechanism uses an oillubricated gearbox or speed changer/reducer, then continuous motor operation at low speed may cause poor lubrication. Avoid such operation.

• Single-phase motors

Single-phase motors are not suitable for inverterdriven variable speed operation. Use three-phase motors.

Environmental conditions

Installation location

Use the inverter in a location with an ambient temperature range of -10°C (14°F) to 50°C (122°F). The inverter and braking resistor surfaces become hot under certain operating conditions. Install the inverter on nonflammable material such as metal. Ensure that the installation location meets the environmental conditions specified in "Environment" in inverter specifications.

Combination with peripheral devices

Installing a molded case circuit breaker (MCCB)

Install a recommended molded case circuit breaker (MCCB) or an earth leakage circuit breaker (ELCB) in the primary circuit of each inverter to protect the wiring. Ensure that the circuit breaker capacity is equivalent to or lower than the recommended capacity.

Installing a magnetic contactor (MC) in the output (secondary) circuit

If a magnetic contactor (MC) is mounted in the inverter's secondary circuit for switching the motor to commercial power or for any other purpose, ensure that both the inverter and the motor are fully stopped before you turn the MC on or off. Remove the surge killer integrated with the MC.

Installing a magnetic contactor (MC) in the input (primary) circuit

Do not turn the magnetic contactor (MC) in the primary circuit on or off more than once an hour as an inverter fault may result. If frequent starts or stops are required during motor operation, use FWD/REV signals.

• Protecting the motor

The electronic thermal facility of the inverter can protect the general-purpose motor. The operation level and the motor type (general-purpose motor, inverter motor) should be set. For high-speed motors or water-cooled motors, set a small value for the thermal time constant to protect the motor.

If you connect the motor thermal relay to the motor with a long cable, a high-frequency current may flow into the wiring stray capacitance. This may cause the relay to trip at a current lower than the set value for the thermal relay. If this happens, lower the carrier frequency or use the output circuit filter (OFL).

Discontinuance of power-factor correcting capacitor
 Do not mount power factor correcting capacitors in
 the inverter (primary) circuit. (Use the DC
 REACTOR to improve the inverter power factor.) Do
 not use power factor correcting capacitors in the
 inverter output circuit (secondary). An overcurrent
 trip will occur, disabling motor operation.

• Discontinuance of surge killer

Do not mount surge killers in the inverter output (secondary) circuit.

Reducing noise

Use of a filter and shielded wires are typical measures against noise to ensure that EMC Directives are met.

· Measures against surge currents

If an overvoltage trip occurs while the inverter is stopped or operated under a light load, it is assumed that the surge current is generated by open/close of the phase-advancing capacitor in the power system.

We recommend connecting a DC REACTOR to the inverter.

Megger test

When checking the insulation resistance of the inverter, use a 500V megger and follow the instructions contained in the Instruction Manual.

Wiring

· Wiring distance of control circuit

When performing remote operation, use twisted shielded wire and limit the distance between the inverter and the control box to 20m (65.6ft).

• Wiring length between inverter and motor

If long wiring is used between the inverter and the motor, the inverter will overheat or trip as a result of overcurrent (high-frequency current flowing into the stray capacitance) in the wires connected to the phases. Ensure that the wiring is shorter than 50m (164ft), If this length must be exceeded, lower the carrier frequency or mount an output circuit filter (OFL). When wiring is longer than 50m (164ft), and sensorless vector control or vector control with speed sensor is selected, execute off-line tuning.

Wiring size

Select cables with a sufficient capacity by referring to the current value or recommended wire size.

Wiring type

Do not use multicore cables that are normally used for connecting several inverters and motors.

Grounding

Securely ground the inverter using the grounding terminal

Selecting inverter capacity

• Driving general-purpose motor

Select an inverter according to the applicable motor ratings listed in the standard specifications table for the inverter. When high starting torque is required or quick acceleration or deceleration is required, select an inverter with a capacity one size greater than the standard.

Driving special motors

Select an inverter that meets the following condition: Inverter rated current > Motor rated current.

Transportation and storage

When transporting or storing inverters, follow the procedures and select locations that meet the environmental conditions that agree with the inverter specifications.

F Fuji Electric Co., Ltd.

Gate City Ohsaki, East Tower, 11-2, Osaki 1-chome, Shinagawa-ku, Tokyo 141-0032, Japan

Phone: +81-3-5435-7057 Fax: +81-3-5435-7420

URL: http://www.fujielectric.com/

Fuji Electric Corp. of America

47520 Westinghouse Drive Fremont, CA 94539, USA

Phone: 510.440.1060 Fax: 510-440-1063 URL: http://www.americas.fujielectric.com

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